TCD210177AE Autonics

Modular 2/4-Channel PID Temperature Controllers with Screw Connector



TMH Series

PRODUCT MANUAL

For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Features

[Common]

- Easy maintenance with detachable body and base terminal
- Power supply and communication with expansion connectors (up to 32 units)

[TMH2/4 Series (Control Module)]

- Multi-channel (2-channel/4-channel) input and output control: Expandable up to 32 units (64-channels/128-channels)
- 50 ms high-speed sampling rate and $\pm 0.3\%$ measurement accuracy
- Simultaneous heating and cooling control function and auto/manual control mode (patent: Korea Patent Registration 10-1624105)

$[{\sf TMHA}\,({\sf Analog}\,{\sf Input}\,/\,{\sf Output}\,{\sf Option}\,{\sf Module})\,]$

- ${\color{gray} \bullet 4\, channels, various \, input \, types/temperature \, ranges/transmission \, outputs } \\$
- 50 ms high-speed sampling rate and \pm 0.3% measurement accuracy

[TMHE (Digital Input / Alarm Output Option Module)]

• 8 digital inputs / 8 alarm outputs

[TMHCT (CT Input Option Module)]

8 CT inputs

[TMHC (Communication Modules)]

- Allows connection of control modules and option modules to master devices $\,$
- Connect up to 32 control/option modules per communication model $\,$

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Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards.
- <u>M</u> symbol indicates caution due to special circumstances in which hazards may occur.

⚠ Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.)
 Failure to follow this instruction may result in personal injury, economic loss or fire.
- Do not use the unit in the place where flammable/explosive/corrosive gas, humidity, direct sunlight, radiant heat, vibration, impact, or salinity may be present.

Failure to follow this instruction may result in explosion or fire.

03. Install on a device panel to use.

Failure to follow this instruction may result in fire.

 Do not connect, repair, or inspect the unit while connected to a power source.

Failure to follow this instruction may result in fire.

05. Check 'Connections' before wiring.

Failure to follow this instruction may result in fire.

 ${\bf 06.\ Do\ not\ disassemble\ or\ modify\ the\ unit.}$

Failure to follow this instruction may result in fire.

⚠ Caution Failure to follow instructions may result in injury or product damage

When connecting the power input and relay output, use AWG 20 (0.50 mm²)
cable or over and tighten the terminal screw with a tightening torque of 0.74
to 0.90 N·m.

When connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 16 cable and tighten the terminal screw with a tightening torque of 0.74 to 0.90 N·m.

Failure to follow this instruction may result in fire or malfunction due to contact failure.

02. Use the unit within the rated specifications.

Failure to follow this instruction may result in fire or product damage

- **03.** Use a dry cloth to clean the unit, and do not use water or organic solvent. Failure to follow this instruction may result in fire or electric shock.
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

 $\label{prop:control} \textit{Failure to follow this instruction may result in fire or product damage}.$

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected accidents.
- Check the polarity of the terminals before wiring the temperature sensor.
 For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and length.
- For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.
- The connection of this unit should be separated from the power line and high voltage line in order to prevent inductive noise.

In case of installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.

The connection of this unit should be separated from the power line and high voltage line in order to prevent inductive noise.

- \bullet Do not apply excessive power when connecting or disconnecting the connectors of the product.
- Switch or circuit breaker should be installed nearby users for convenient control.
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature controller.
- · When changing the input sensor, turn off the power first before changing. After changing the input sensor, modify the value of the corresponding parameter.
- Power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Do not overlapping communication line and power line. Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- · Make a required space around the unit for radiation of heat.
- For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- · Mounting multiple devices in any way other than the specified mounting method may cause heat to build up inside, which will shorten their service life. If there is a possibility of the ambient temperature rising to a temperature above the specified temperature range, take steps, such as installing fans, to cool the device. Be sure that the cooling method in not cooling just the terminal block. If only the terminal block is cooled, measurement errors may occur.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- Do not wire to terminals which are not used.
- Install DIN rail vertically from the ground.
- This unit may be used in the following environments.
- Indoors (in the environment condition rated in 'Specifications')
- Altitude max 2.000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations. For selecting the specified model, follow the Autonics website.

■ Control module

T 6 М

Channel

2: 2 channels 4: 4 channels

Control output

R: Relay output S: SSR drive output

C: Selectable current or SSR drive output

Alarm output

2: Alarm output 1/2 (2 channels) 4: Alarm output 1/2/3/4 (2 channels)

N: None (4 channels)

Power supply

6 Module type

B: Basic module E: Expansion module

 Since the expansion module is not supplied with power/comm. terminal. Use it with the basic

2: 24 VDC=

Option module

Model	Input	Output
TMHA-42AE	Temperature sensor / Analog input 1 to 4	Transmission output (0/4 - 20 mA) 1 to 4
TMHE-82RE	Digital input 1 to 8	Alarm output 1 to 8
TMHCT-82NE	CT input 1 to 8	-

■ Communication module

Model	Connection type	Protocol		
TMHC-22LE	RS422, RS485	Modbus RTU, PLC Ladderless communication		
TMHC-22EE	Ethernet (10/100BaseT)	Modbus TCP		

Product Components

Product (+ bracket)

· Instruction manual

• Expansion connector \times 1

• Module lock connector × 2

Firmware Version and Manual

Additional settings may be required if the firmware version is different between the connected modules.

Please refer to the user manual and the user manual for communication, and be sure to follow cautions written in the technical descriptions.

Visit our website (www.autonics.com) to download manuals.

Software

Download the installation file and the manuals from the Autonics website.

DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

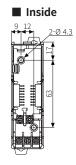
Sold Separately

- Current transformer (CT)
- CT connector cable: CICT4-
- Communication Converters: SCM-USP / SCM-38I / SCM-US48I / SCM-WF48

Dimensions

• Unit: mm, For the detailed drawings, follow the Autonics website.

Side ■ Front 110



Specifications

■ Control module

Model	TMH2	TMH4							
No. of channels	2 channels	4 channels							
Sampling period	50 ms (2 channels or 4 channels synchronous sampling)								
Input specification	Thermocouple, RTD, Analog (refer to 'Inpu	t Specification')							
T input • 0.0 - 50.0A (primary current measurement range) • CT ratio: 1/1,000, • Measurement accuracy: ±5% F.S. ±1 digit • Connect input									
Digital input	• Connect input $ ON: \leq 1 \text{ k}\Omega, \text{ OFF: } \geq 100 \text{ k}\Omega $ • Solid state input $ Residual \text{ voltage: } \leq 0.9 \text{ V}, $ • Leakage current: $\leq 0.5 \text{ mA} $ • Outflow current: $\approx 0.3 \text{ mA per input} $								
Control type	Heating, cooling, heating & cooling: ON/O	FF, P, PI, PD, PID control							
Control output	• Relay: 250 VAC ~ 3 A 1a mechanical life cycle: ≥ 10,000,000 operations, electrical life cycle: ≥ 100,000 operations • SSR: 12 VDC = ±3 V, ≤ 20 mA • Current ⁰¹ : DC 4 - 20 mA or DC 0 - 20 mA (Load: ≤ 500 Ω)								
Alarm output	250 VAC~ 3 A 1a Mechanical life cycle: ≥ 10,000,000 operations Electrical life cycle: ≥ 100,000 operations								
Communication	Modbus RTU								
Hysteresis	• Thermocouple / RTD: 1 to 100 (0.1 to 100 • Analog: 1 to 100 digit	°C/°F							
Proportional band (P)	• Thermocouple / RTD: 1 to 999 (0.1 to 999 • Analog: 0.1 to 999.9 digit	.9) °C/°F							
Integral time (I)	0 to 9,999 sec								
Derivative time (D)	0 to 9,999 sec								
Control period (T)	• Relay output, SSR drive output: 0.1 to 120 • Selectable current or SSR drive output: 1								
Manual reset	0 to 100 (0.0 to 100.0) %								
Insulation type	Double insulation or reinforced insulation between the measuring input part and the								
Unit weight (packaged)	Beside module: ≈ 178 g (≈ 251 g) • Expansion module: ≈ 173 g (≈ 246 g)								

⁰¹⁾ When the control output is set to the current output, the heater current value monitoring function through the CT input terminals is not available.

Option module

Model	TMHA-42AE						
No. of channels	4 channels						
Sampling period	50 ms (4 channels synchronous sampling)						
Input specification	pecification Thermocouple, RTD, analog (refer to 'Input Specification')						
Transmission output DC 4 - 20 mA or DC 0 - 20 mA (Load: \leq 500 Ω)							
Communication	Modbus RTU						
Insulation type Double insulation or reinforced insulation (mark: , dielectric stret between the measuring input part and the power part: 1 kV)							
Unit weight (packaged) $\approx 161 \mathrm{g} (\approx 234 \mathrm{g})$							

Model	TMHE-82RE	TMHCT-82NE				
No. of channels	8 points	8 points				
Input specification	- Digital input • Connect input • On: ≤ 1 kΩ, OFF: ≥ 100 kΩ • Solid state input Residual voltage: ≤ 0.9 V, Leakage current: ≤ 0.5 mA • Outflow current: ≈ 0.3 mA per input	-CT input • 0.0-50.0 A (primary current measurement range) • CT ratio: 1/1,000 • Measurement accuracy: ±5% F.S. ±1 digit				
Alarm output	250 VAC ~ 3 A 1a, • Mechanical life cycle: ≤ 10,000,000 operations • Electrical life cycle: ≤ 100,000 operations	-				
Communication	Modbus RTU					
Insulation type	-					
Unit weight (packaged) $\approx 166 \text{ g} (\approx 239 \text{ g})$ $\approx 148 \text{ g} (\approx 221 \text{ g})$						

■ Communication module

Model		TMHC-22LE	TMHC-22EE			
	COM1	Connection type: RS422 / RS485 Protocol: Modbus RTU,	Connection type: Ethernet			
Communi -cation	COM2	PLC Ladderless communication	(10/100BaseT) • Protocol: Modbus TCP			
	PC loader	TTL (Protocol: Modbus RTU)				
Insulation type		Double insulation or reinforced insulation (mark: 回, dielectric strubetween the measuring input part and the power part: 1 kV)				
Unit weight		≈ 147 g (≈ 219 g)	≈ 129 g (≈ 200 g)			

■ Common

■ Common				
Power supply 01)	24 VDC==			
Permissible voltage	90 to 110% of rated voltage			
range	<u> </u>			
Power Consumption				
Display type	None- parameter setting and monitoring is available at external devices			
Memory retention	≈ 10 years (non-volatile semiconductor memory type)			
Insulation resistance	100 MΩ (500 VDC== megger)			
Dielectric strength	Between the charging part and the case: 1,000 VAC \sim 50/60 Hz			
Dietectric strength	for 1 min			
Vibration	0.75mm amplitude at frequency of 5 to 55Hz in each X, Y, Z direction for 2 hours			
Noise immunity	Square shaped noise by noise simulator (pulse width 1 μ s) ± 0.5 kV			
Ambient	-10 to 50 °C, storage: -20 to 60 °C (no freezing or condensation)			
temperature	-10 to 50° C, storage: -20 to 00° C (no freezing or condensation)			
Ambient humidity	35 to 85%RH, Storage: 35 to 85%RH (no freezing or condensation)			
Protection structure	IP20 (IEC standard)			
Certification	IHI ௵ (RF) ≥ 3			

01) The control extension/option/communication module uses the power voltage from the control basic module.

Input Specifications

■ Input type and range

The setting range of some parameters is limited when using the decimal point display.

Input type	!	Decimal point	Display Method	Input rai	(°C)	Input range (°F)				
	K (CA)	1	K (CA) .H	-200	to	1,350	-328	to	2,463	
	IX (CA)	0.1	K (CA) .L	-200.0	to	1,350.0	-328.0	to	2463.0	
	J (IC)	1	J (IC) .H	-200	to	800	-328	to	1,472	
	3 (10)	0.1	J (IC) .L	-200.0	to	800.0	-328.0	to	1472.0	
	E (CR)	1	E (CR) .H	-200	to	800		to	1,472	
	L (CIV)	0.1	E (CR) .L	-200.0	to	800.0		to	1,472.0	
	T (CC)	1	T (CC) .H	-200	to	400	-328	to	752	
	1 (CC)	0.1	T (CC) .L	-200.0	to	400.0	-328.0	to	752.0	
Thermo	B (PR)	1	B (PR)	0	to	1,800	32	to	3,272	
-couple	R (PR)	1	R (PR)	0	to	1,750	32	to	3,182	
-couple	S (PR)	1	S (PR)	0	to	1,750	32	to	3,182	
	N (NN)	1	N (NN)	-200	to	1,300	-328	to	2,372	
	C (TT)	1	C (TT)	0	to	2,300	32	to	4,172	
	G (TT)	1	G (TT)	0	to	2,300	32	to	4,172	
	L (IC)	1	L (IC) .H	-200	to	900	-328	to	1,652	
		0.1	L (IC) .L	-200.0	to	900.0	-328.0	to	1,652.0	
	U (CC)	1	U (CC) .H	-200	to	400	-328	to	752	
	` '	0.1	U (CC) .L	-200.0	to	400.0	-328.0	to	752.0	
	Platinel II	1	PLII	0	to	1,390	32	to	2,534	
	Cu50 Ω	0.1	CU 50	-200.0	to	200.0	-200.0	to	392.0	
	Cu100 Ω	0.1	CU 100	-200.0	to	200.0	-200.0	to	392.0	
	JPt100 Ω	1	JPt100.H	-200	to	650	-328	to	1,202	
RTD	JF (100 \(\)2	0.1	JPt100.L	-200.0	to	650.0	-328.0	to	1,202.0	
KID	DPt50 Ω	0.1	DPt50.L	-200.0	to	600.0	-328.0	to	1,202.0	
	DPt100 Ω	1	DPt100.H	-200	to	650	-328	to	1,202	
	DP(100 12	0.1	DPt100.L	-200.0	to	650.0	-328.0	to	1,202.0	
	Nickel120 Ω	1	NI12	-80	to	260	-112	to	500	
	0 to 10 V	-	AV1				10 V			
	0 to 5 V	-	AV2				5 V			
Analog	1 to 5 V	-	AV3			1 ~	5 V			
Allalog	0 to 100 mV	-	AMV1				100 mV			
	0 to 20 mA	-	AMA1			0 ~	20 mA			
	4 to 20 mA	-	AMA2			4 ~	20 mA			

- Permissible line resistance per line: $\leq 5~\Omega$

■ Measurement accuracy

Input type	Using temperature	Measurement accuracy			
Thermo -couple	At room temperature (23 ±5 °C)	$\label{eq:continuous} \begin{array}{l} (\text{PV}\pm0.3\%\text{or}\pm1^\circ\text{C}\text{higher}\text{one})\pm1\text{-digit} \\ \bullet.\text{Thermocouple K, J, T, N, E}\text{below}-100^\circ\text{C}\text{and L, U, PLII, RTD Cu50}\Omega, \text{DPt50}\Omega; \\ (\text{PV}\pm0.3\%\text{or}\pm2^\circ\text{C}\text{higher}\text{one})\pm1\text{-digit} \\ \bullet.\text{Thermocouple C, G}\text{and R, S}\text{below}200^\circ\text{C}; \\ (\text{PV}\pm0.3\%\text{or}\pm3^\circ\text{C}\text{higher}\text{one})\pm1\text{-digit} \\ \bullet.\text{Thermocouple B}\text{below}400^\circ\text{C}; \text{there is no accuracy standards} \end{array}$			
RTD	Out of room temperature range	$ \begin{array}{l} (\text{PV}\pm 0.5\% \text{ or } \pm 2^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{RTD Cu50 } \Omega, \text{ DPt50 } \Omega; \\ (\text{PV}\pm 0.5\% \text{ or } \pm 3^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{Thermocouple R, S, B, C, G:} \\ (\text{PV}\pm 0.5\% \text{ or } \pm 5^{\circ}\text{C higher one}) \pm 1\text{-digit} \\ \bullet \text{Other sensors:} \leq \pm 5^{\circ}\text{C } (\leq -100^{\circ}\text{C}) \end{array} $			
Al	At room temperature $(23 \pm 5 ^{\circ}\text{C})$	$\pm 0.3\%$ F.S. ± 1 -digit			
Analog	Out of room temperature range	±0.5% F.S. ±1-digit			

 $[\]bullet \ \ Connecting 1 \ or \ more \ expansion \ module \ can \ vary \ measurement \ accuracy \ about \ \pm 1^{\circ}\text{C}, \ regardless \ of the \ number \ of \ connected \ expansion \ module.$

Communication Setting

■ Interface

Module	Control	Option	Communicatio	n							
Series	ТМН2/4	TMHA, TMHE, TMHCT	TMHC-22LE	TMHC-22EE							
Protocol	Modbus RTU	Modbus RTU, PLC Ladderless communication	Modbus TCP								
Comm. method	RS485	RS422, RS485	Ethernet (10/100BaseT)								
Maximum connection	32 units (address: 01 to 32) •16 units in case of connecting TMHC module (address: 01 to 16)	16 units, option s per each									
Synchronization	Asynchronous	-									
Connection method	Two-wire half duplex		-								
Comm. effective range	≤ 800 m			-							
Comm. speed	4,800 / 9,600 (default) / 19,20 (parameter)	00 / 38,400 / 1	15,200 bps	10/100 Mbps							
Response time	5 to 99 ms (default: 20 ms)			-							
Start bit	1 bit (fixed)			=							
Data bit	8 bit (fixed)			-							
Parity bit	None (default) , Odd, Even	None (default) , Odd, Even									
Stop bit	1 bit, 2 bit (default)			-							
EEPROM life cycle		. bit, 2 bit (default) - TMH2/4, TMHC-22LE: ≈ 1,000,000 operations (Erase / Write) Other models: Not applicable									

- When changing the setting value related to communication interface, reboot the device for normal operation.
 It is recommended to use Autonics communication converter. Please use twisted pair wire, which is suitable for RS485 communication.
 - Address

Set the communication address with the communication address setting switch (SW1, default: 1) and communication address group switch (SW2, default: +0, TMH2/4 series).

	SW1								į	Ď.							
Series		0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
TMH2/4	+0 +16	16	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
1МП2/4	■ +0 +16	32	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
ТМНС		16	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
TMHA		48	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47
TMHE		64	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63
TMHCT		80	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79

When connecting TMHC and TMH2/4 to master separately, communication address can be duplicated, but if they communicate with master at the same time, communication address must not be duplicated to avoid error. (use address TMHC: 1 to 16, TMH2/4: 17 to 32)

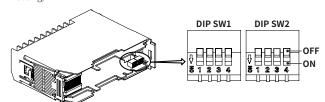
■ Mac address [Ethernet communication module]

It is possible to check Mac address for Ethernet communication at DAQMaster. Refer to the manual for the details.

■ DIP switch setting [Ladderless communication module]

After separating base terminal block, set communication speed, stop bit, PLC connection and protocol by using a internal DIP switch.

 Setting values are applied to COM1 only, default: All switches OFF (following parameter setting)



DIP SW1

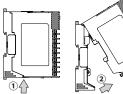
1	2	Communication speed	3	4	Stop bit
OFF	OFF	Following parameter setting	OFF	OFF	Following parameter setting
OFF	ON	19,200 bps	OFF	ON	Stop bit: 1 bit
ON	OFF	38,400 bps	ON	OFF	Stop bit: 2 bit
ON	ON	115,200 bps	ON	ON	-

DIP SW2

1	2	3	4	PLC connection and protocol
OFF	OFF	OFF	OFF	Following parameter setting
OFF	OFF	OFF	ON	Modbus RTU
OFF	OFF	ON	OFF	LS MASTER-K series special protocol
OFF	OFF	ON	ON	LS GLOFA-GM series special protocol
OFF	ON	OFF	OFF	LS XGT/XGB series special protocol
OFF	ON	OFF	ON	MITSUBISHI MELSEC series special protocol Q/QnACPU common command (1401/0401)
OFF	ON	ON	OFF	MITSUBISHI MELSEC series special protocol ACPU common command (WW/WR)
OFF	ON	ON	ON	OMRON SYSMAC series special protocol
ON	OFF	OFF	OFF	MITSUBISHI MELSEC3 series special protocol

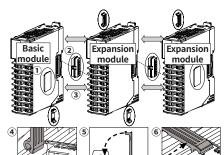
Installation Method

■ Separating base terminal block



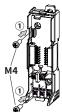
- 1. Push the lock lever at ①.
- 2. Pull the body of the module to ② direction.
- When connecting base terminal block, align the upper concave part (凹) of the body and the upper convex part (凸) of the base. If the upper parts are not align correctly, it may damage to the inner connector.

■ Connection between modules



- 1. Remove END cover (1) of each module (except END cover of the first and last module).
- 2. 2 Insert expansion connector (2) and connect them tightly to ③ direction (max. 31 units).
- 3. Insert module lock connector (4) to lock connector hole (5).
- 4. Push module lock connector to the lock direction (6).
- Supply adequate power for power input specifications and overall capacity. (Max. power when connecting 32 modules: $32 \times 5 \text{ W} = 160 \text{ W}$)

Mounting with bolts



- 1. Refer to 'Separating base terminal block' to separate base terminal block.
- 2. Install the module by using M4 screws to the ① direction of the inside mounting hole.
- Refer to the 'Dimensions' to check hall positions and dimensions of inside mounting hole.

■ Mounting on DIN rail

- Installation



1. Press the rail lock at the top / bottom of the module to the $\ensuremath{\mbox{\circlearrowleft}}$ direction.



- 2. Hang the top rail lock to DIN rail.
- 3. Push to 1 direction and press to 2 direction.

- Separation



- 1. Press the module to ① direction.
- 2. Keep it pressed and pull it to ② direction.

Precautions

- Install the module vertically.
- Use end plates (sold separately, not available from Autonics) to fix firmly.

Terminal

• Unit: mm, Use ring or spade terminal as below.





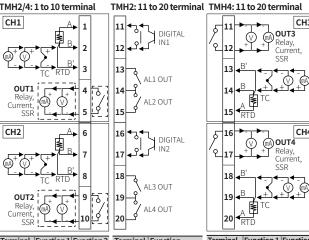


Ring terminal

Connections

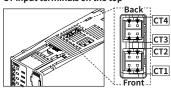
■ Control module

TMH2/4: 1 to 10 terminal

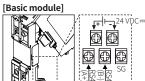


								_					_
Tei	minal	Functio	n 1	Functio	n 2	Terminal	Function	Ter	minal	Functio	n 1	Function	n 2
1			Α	-		11	Digital input 1	11	CH3	Relay,	_		
2	CH1	RTD	В	TC,	+	12	Digital Iliput 1		output	current,	+	-	
3	input	KID	B'	current,		13	Alarm output 1		output	SSR	Ľ		_
_			_	voltage		14	Ground	13			B'	TC,	_
4	K H I	Relay,	+			15	Alarm output 2	14	CH3	RTD	В	current,	+
5		current, SSR	<u> </u>	-		16	B I	15	input		A	voltage	_
6		22K			_	17	Digital input 2			D 1	А	-	
-	CH2		A	TC.	_	18	Alarm output 3	16	CH4	Relay, current,	_		
-	input	RTD	В	TC,	+	19	Ground	17	output	SSR	+	_	
8	IIIput		B'	current, voltage	-	20	Alarm output 4	18		33IX	B'	TC,	\Box
9		Relay,	+	voltage	_				CH4		-	current.	-
	CHZ	current.		_				19	input	RTD	В	voltage	+
10		SSR	-					20			Α	-	

CT input terminals on the top



Power/Comm. terminal on the back



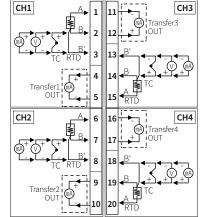
CT connector cable



Pin	Cable color	CT connection
1	Brown	CT 2 / 4
2	Blue	CT 2 / 4
3	White	CT 1 / 3
4	Black	CT 1 / 3
4		- , -

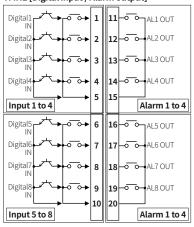
Option module

TMHA [Analog input / output]



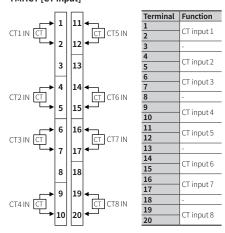
_						
Ter	minal	Functio	n 1	Function 2		
1	CUI		Α	-		
2	CH1 input	RTD	В	TC, current, +		
3	IIIput		B'	voltage —		
4	CH1		+			
5	output	Current	_	-		
6	CLIO		Α	-		
7	CH2	RTD	В	TC, current, +		
8	input		В'	voltage –		
9	CH2	C	+			
10	output	Current	_	1-		
11	CH3	Current	_			
12	output	Current	+	1-		
13	01.10		B'	TC, current, -		
14	CH3 input	RTD	В	voltage +		
15	IIIput		Α	-		
16	CH4		_			
17	output	Current	+	1-		
18			В'	TC, current, -		
19	CH4	RTD	В	voltage +		
20	input		Α	-		

TMHE [Digital input / Alarm output]



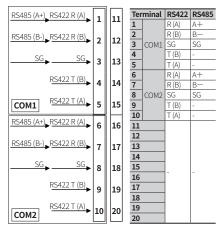
Terr	ninal	Function		
1		Digital input 1		
1 2 3	Input 1 to 4	Digital input 2		
		Digital input 3		
4		Digital input 4		
5		Ground		
6		Digital input 5		
7		Digital input 6		
8	Input 5 to 8	Digital input 7		
9		Digital input 8		
10		Ground		
11		Alarm output 1		
12		Alarm output 2		
13	Output 1 to 4	Alarm output 3		
14		Alarm output 4		
15		Ground		
16		Alarm output 5		
17	Output 5 to 8	Alarm output 6		
18		Alarm output 7		
19		Alarm output 8		
20		Ground		

TMHCT [CT input]



■ Communication module

TMHC-22LE [Ladderless comm.]



TMHC-22EE [Ethernet comm.]



Errors

Indicator

Name	Status	Color	Description	Troubleshooting
PWR	ON	Red	☐ channel error: Input < Input range, Input > Input range,	When the error factor is resolved, it automatically
CH□	Flash ⁰¹⁾	Red	Input sensor is open or not connected	returns to normal operation.

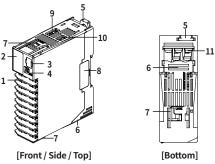
01) Cycle: 0.5 sec

■ Communication output, DAQMaster

Communication output (decimal)	DAQMaster	Description	Troubleshooting	
'31000'	Display 'OPEN'	Input sensor is open or not connected	When the error factor is	
'30000'	Display 'HHHH' 01)	Input > Input range	resolved, it automatically returns to normal operation.	
'-30000'	Display 'LLLL' 01)	Input < Input range	retains to normal operation	
'31500'	Display '31500'	Sensor internal communication error	Check the power supply (24VDC==). (22)	

When HHHH / LLLL error occurs, the control output may occur by recognizing the maximum or minimum input depending on the control type. Please be careful.
 This error may occur when connecting only the loader port.

Unit Descriptions



1. Input / Output Terminal

Refer to 'Connection' for the details about terminal description.

2. Indicator

- Control module: TMH2

controtmodu								
			Control	Auto	Alarm output			
	Status	Initial power ON 01)	output	tuning 02)	N.O.		N.C	
Indicator			output	tuillig	OFF	ON	OFF	ON
LED1LED2 PWR	(green) 03)		ON	ON				
CH1			ON	Flash				
PWR CH2	(red)	-	ON	Flash	-			
(red)			ON 04)	OFF				
CH1 AL1 (red)			ON 05)	OFF				
CH 2 AL 2 (yello	ow)	Flash (4,800 bps)	Module c	ommunica	tion sta	atus ⁰⁶⁾		
	(yellow)	Flash (9,600 bps)	-	-	OFF	ON	OFF	ON
AL3 AL2	(yellow)	Flash (19,200 bps)	-	-	OFF	ON	OFF	ON
AL3 ((yellow)	Flash (38,400 bps)	-	-	OFF	ON	OFF	ON
AL4	(vellow)	Flash (115,200 bps)	-	-	OFF	ON	OFF	ON

- Control module: TMH4

Indicato			Initial power ON 01)	Control output	Auto tunning 02)
LED 1 LED 2		PWR (green) 03)		ON	ON
	-	CH1 (red)		ON	Flash
PWR		CH2 (red)	-	ON	Flash
	\neg	CH3 (red)		ON	Flash
CH1		CH4 (red)		ON	Flash
CH 2		(yellow)	Flash (4,800 bps)	Module communicatio	n status ⁰⁶⁾
	7	(yellow)	Flash (9,600 bps)	-	-
CH 3		(yellow)	Flash (19,200 bps)	=	-
	\neg	(yellow)	Flash (38,400 bps)	-	-
CH 4		(yellow)	Flash (115,200 bps)	-	-

- Option module: TMHA [Analog input / output]

Indicato	r		Initial power ON 01)	Internal comm.	Transmission output
LED 1 LED 2		PWR (green) 07)		ON	ON
	_	CH1 (red)		-	ON
PWR		CH2 (red)	-	-	ON
	=	CH3 (red)		-	ON
CH 1		CH4 (red)		-	ON
CH 2		(yellow)	Flash (4,800 bps)	Module communicatio	n status ⁰⁶⁾
	7	(yellow)	Flash (9,600 bps)	ON (CH1)	-
CH 3		(yellow)	Flash (19,200 bps)	ON (CH2)	-
	ا آ	(yellow)	Flash (38,400 bps)	ON (CH3)	-
CH 4		(yellow)	Flash (115,200 bps)	ON (CH4)	-

- Option module: TMHE [Digital input, Alarm output]

			Internal	Alarm o	utput		
	Status	Initial power ON 01)	comm.	N.O.		N.C.	
Indicator			COIIIII.	Open	Closed	Open	Closed
LED 1 LED 2	PWR (green) 07)		ON	ON			
	AL1 (red)		-	OFF	ON	OFF	ON
PWR	AL2 (red)	-	-	OFF	ON	OFF	ON
AL 1 AL 5	AL3 (red)		-	OFF	ON	OFF	ON
AL1 AL5	AL4 (red)		-	OFF	ON	OFF	ON
AL2 AL6	(yellow)	Flash (4,800 bps)	Module co	ommunic	ation stat	tus ⁰⁶⁾	
	√ AL5 (yellow)	Flash (9,600 bps)	-	OFF	ON	OFF	ON
AL3 AL7	AL6 (yellow)	Flash (19,200 bps)	-	OFF	ON	OFF	ON
	AL7 (yellow)	Flash (38,400 bps)	-	OFF	ON	OFF	ON
AL4 AL8	AL8 (yellow)	Flash (115,200 bps)	-	OFF	ON	OFF	ON

- Option module: TMHCT [CT input]

Indicator		Initial power ON 01)	CT input ⁰⁸⁾	Internal comm.
LED 1 LED 2	PWR (green) 07)		ON	ON
	⊣ (red)		ON (40.1 to 50.0 A)	-
PWR	⊕ (red)	-	ON (30.1 to 40.0 A)	-
	(red)		ON (20.1 to 30.0 A)	-
	(red)		ON (10.1 to 20.0 A)	-
	(yellow)	Flash (4,800 bps)	Module communication	n status ⁰⁶⁾
	(yellow)	Flash (9,600 bps)	ON (40.1 to 50.0 A)	-
	음 (yellow)	Flash (19,200 bps)	ON (30.1 to 40.0 A)	-
	(yellow)	Flash (38,400 bps)	ON (20.1 to 30.0 A)	-
	(yellow)	Flash (115,200 bps)	ON (10.1 to 20.0 A)	-

- Communication module: TMHC-22LE [Ladderless communication]

Indicator	r	Status	Initial power ON 09)	Internal comm.	Connection	Ladderless communication
LED1LED2 PWR		PWR	Flash (4,800 bps)	Flash (green)		Flash (red, read operation)
	LED 1	(red)	Flash (9,600 bps)	Flash (TMH2/4)		-
		(red)	Flash (19,200 bps)	Flash (TMHA)	-	-
		(red)	Flash (38,400 bps)	Flash (TMHE)		-
		(red)	Flash (115,200 bps)	Flash (TMHCT)		
		(yellow)	Flash (4,800 bps)		ON	Flash (send operation)
) 2	(yellow)	Flash (9,600 bps)		ON (TMH2/4)	-
		(yellow)	Flash (19,200 bps)]-	ON (TMHA)	-
		(yellow)	Flash (38,400 bps)		ON (TMHE)	-
		(yellow)	Flash (115,200 bps)		ON (TMHCT)	-

- Communication module: TMHC-22EE [Ethernet communication]

Indicator	Status	Initial power ON	Internal comm.	Connection
LED 1 LED 2	PWR (green)	ON	Flash (external device)	
	(red)	-	Flash (TMH2/4)	-
PWR 1	(red)		Flash (TMHA)	
	(red)		Flash (TMHE)	
3 3	(red)	-	Flash (TMHCT)	
	(yellow)	-	ON	Flash (Ethernet comm.)
	(yellow)	Sequence-flashing vertically for 5 sec	-	ON (TMH2/4)
	(yellow)		-	ON (TMHA)
	(yellow)		-	ON (TMHE)
	(yellow)		-	ON (TMHCT)

- 01) At the moment when power is on, the indicator of set communication speed flashes for 5 sec.
- 02) Indicator of the channel, which is in the process of auto-tuning, flashes at 1 sec interval.
- 03) When communicating with external device, PWR indicator flashes
- 04) Turns on, when CH1 outputs cooling control in the heating&cooling control method.
- 05) Turns on, when CH2 outputs cooling control in the heating&cooling control method
- 06) ON: Internal comm. (normal) Flash: Internal comm. (abnormal) OFF: not communicating
- 07) 1 sec interval flash: external comm. (normal) ON: Internal comm. (normal) Flash: Internal comm. (abnormal) OFF: not Internal communicating
- 08) The indicator corresponding to the certain setting value of CT input flashes according to the parameter.
 LED 1: CT Input Value Indication Lamp1 LED 2: CT Input Value Indication Lamp2
- 09) At the moment when power is ON, the indicator of communication speed flashes for 5 sec at 1 sec interval. • LED 1: HOST 1 • LED 2: HOST 2

3. PC loader port

PC loader port supports serial communication between single module and PC. It needs communication converter(SCM-USP) for communicating.

4. Communication address setting switch (SW1)

Set the communication address. If changing the communication address by setting switch, use the flat head driver which is 2mm size or plastic driver. If not, it may cause

5. Rail lock

Rail lock helps installing the device. Refer to 'Installation Method' for the details.

6. Lock lever

Lock lever holds module body and base tightly.

7. Module lock connector hole

When connecting modules, insert module lock connector in the hole in order to enhance coherence between them.

8. END Cover

When connecting modules, remove END cover in order to connect expansion connector.

9. CT input Terminal [Control module]

Refer to 'Connection' for the details.

9. Communication mode switch (SW2) [Ladderless communication module] Select communication mode between RS485 and RS422.

10. Communication address group switch (SW2) [Control module] When setting the communication address over 16, select +16.

11. Power / Communication terminal [Control basic module]

Supplies power to both basic control/expansion module and communicates with one or more module.

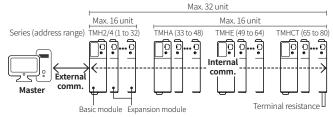
Configuration Example

TMH2/4 expansion module, TMHA, TMHE and TMHCT are should be used with TMH2/4 basic module.

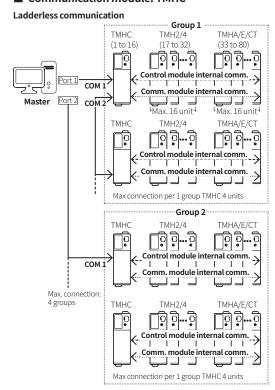
Each module is available to monitoring at DAQMatser via PC loader.

- Internal comm.: Receiving/Sending data between TMH2/4 and TMHA/E/CT
- External comm.: Communication with master for controlling

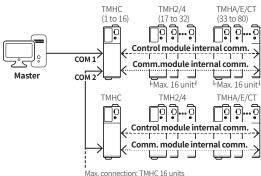
■ Control module: TMH2/4, Option module: TMHA/E/CT inter-working



Communication module: TMHC



Ethernet communication

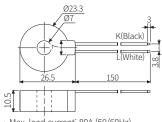


Sold Separately: Current Transformer (CT)

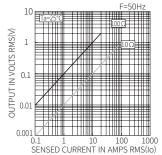
- \bullet The current for above CTs is 50A same but inner hole sizes are different. Please use this for your environment.

 • Do not supply primary current in case that CT output is open. High voltage will be

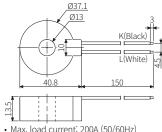
CSTC-E80LN



- Max. load current: 80A (50/60Hz)
- Current ratio: 1/1000• Wire wounded resistance: $31\Omega \pm 10\%$



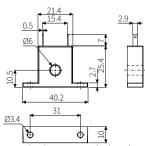
CSTC-E200LN



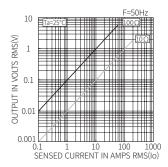
- Max. load current: 200A (50/60Hz)
- Current ratio: 1/1000
- Wire wounded resistance: $20\Omega\pm10\%$

OUTPUT IN VOLTS RMS(V) 0.1 0.001 SENSED CURRENT IN AMPS RMS(Io)

CSTS-E80PP

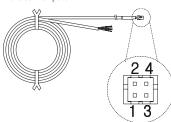


- Max. load current: 80A (50/60Hz) Current ratio: 1/1000
- Wire wounded resistance $31\Omega \pm 10\%$



Sold Separately: CT Connector Cable

• When connecting CT connector and CT input terminal, align the concave part and the convex part.



Model	Cable length		
CICT4-1	1 m		
CICT4-3	3 m		